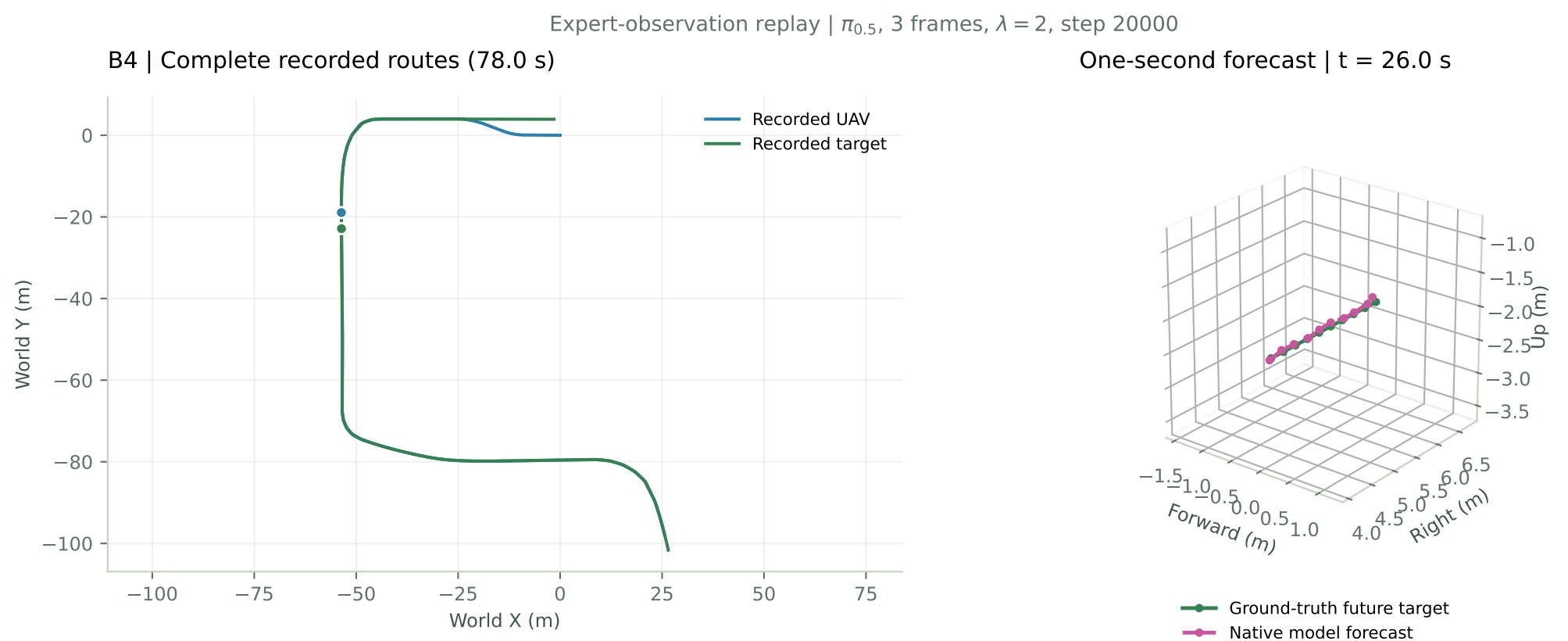
Expert-observation replay | $\pi_{0.5}$, 3 frames, $\lambda = 2$, step 20000
B4 | Complete recorded routes (78.0 s)
Recorded UAV
Recorded target
World Y (m)
World X (m)
0
−20
−40
−60
−80
−100
−100
−75
−50
−25
0
25
50
75
One-second forecast | t = 26.0 s
Forward (m)
Right (m)
Up (m)
−1.5
−1.0
−0.5
0.0
0.5
1.0
4.0
4.5
5.0
5.5
6.0
6.5
−1.0
−1.5
−2.0
−2.5
−3.0
−3.5
Ground-truth future target
Native model forecast