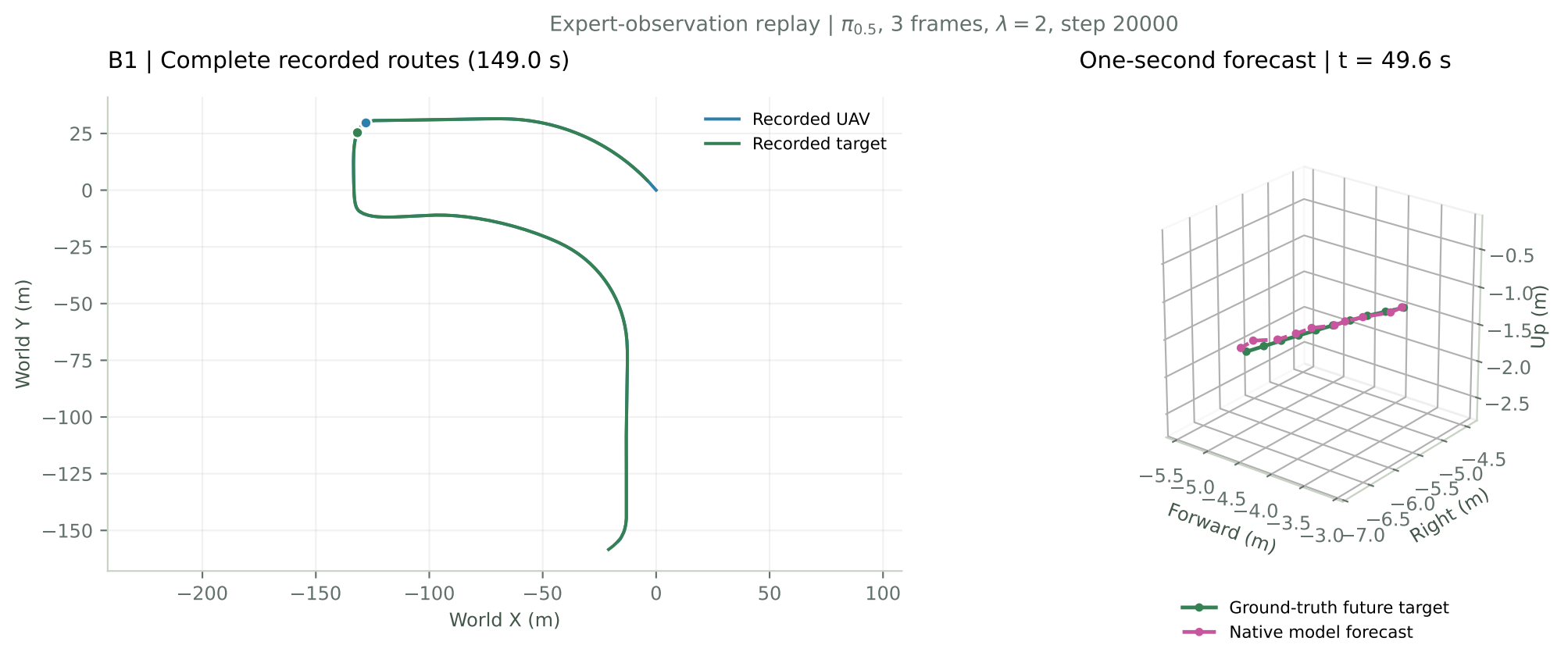
Expert-observation replay | $\pi_{0.5}$, 3 frames, $\lambda = 2$, step 20000
B1 | Complete recorded routes (149.0 s)
Recorded UAV
Recorded target
World Y (m)
World X (m)
25
0
−25
−50
−75
−100
−125
−150
−200
−150
−100
−50
0
50
100
One-second forecast | t = 49.6 s
Up (m)
−0.5
−1.0
−1.5
−2.0
−2.5
Forward (m)
Right (m)
−5.5
−5.0
−4.5
−4.0
−3.5
−3.0
−7.0
−6.5
−6.0
−5.5
−5.0
−4.5
Ground-truth future target
Native model forecast