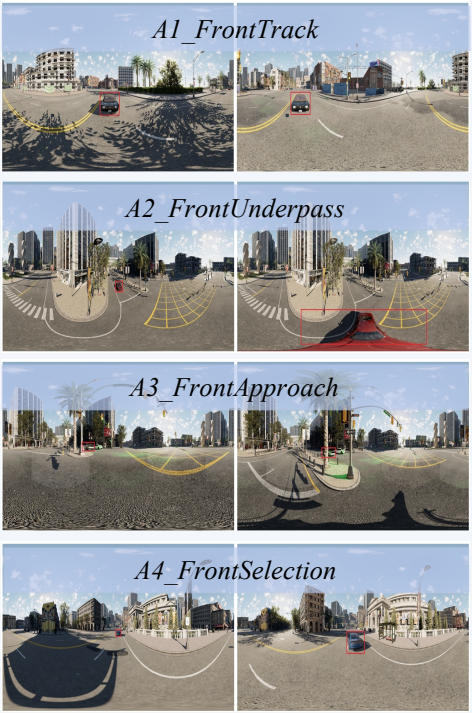
360UAV-ETrack

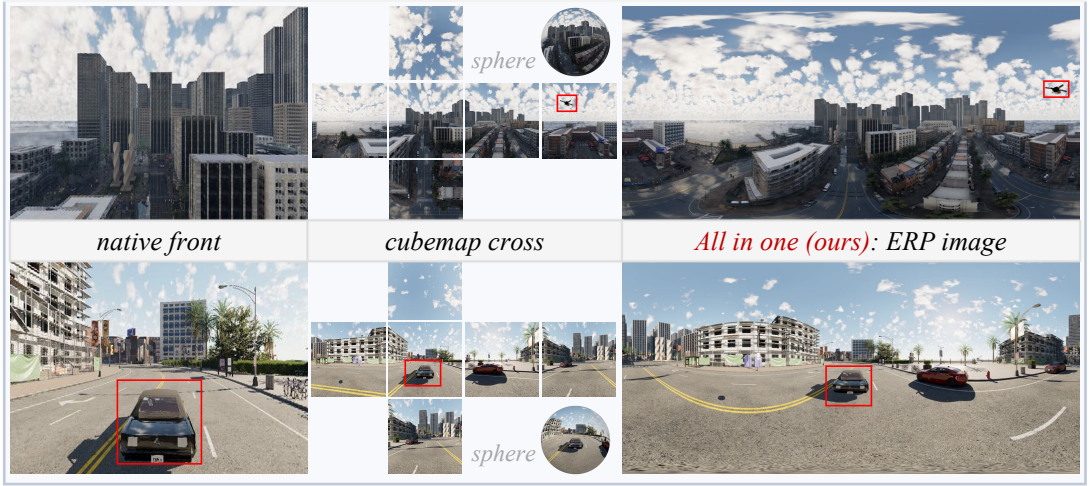
360° Embodied UAV — Tracking Without Turning

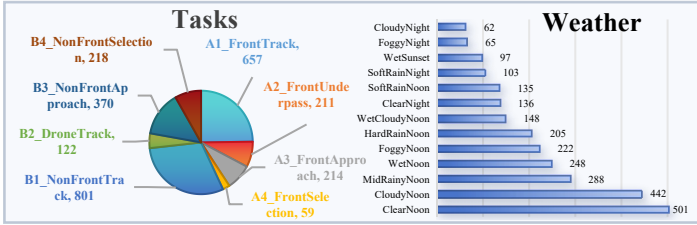
PartA: front init



PartB: nonfront init







Metric Values

metric	value
Sequences	2652
ERP frames	1.73M+
Duration	48.16h
Task types	8
Weather	13

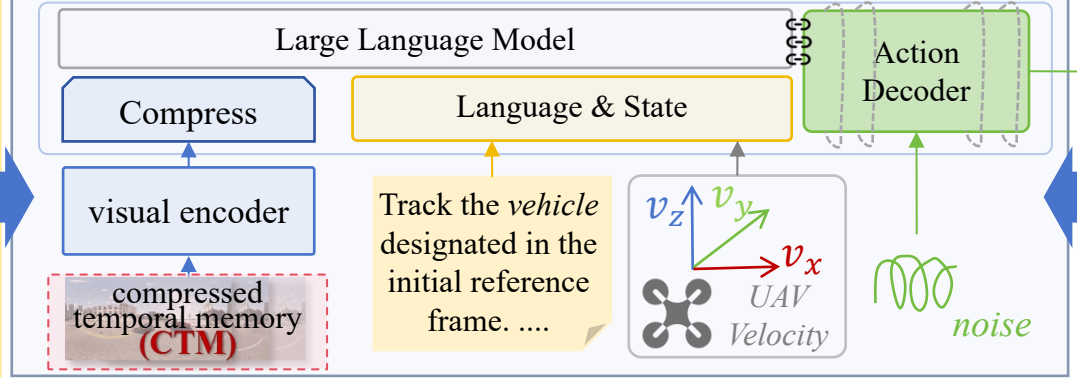
360UAV-TVLA

Multimodal Tracking *Input*



UAV State $[v_x, v_y, v_z]$
$[1.2,\ 0.0, -0.3]$ *m/s*

Tracking Instructions
Track the *vehicle designated*.....



Embodied Tracking *Supervision*

a_1 a_2 a_3 a_h

$h \times 3$ continuous action chunk

