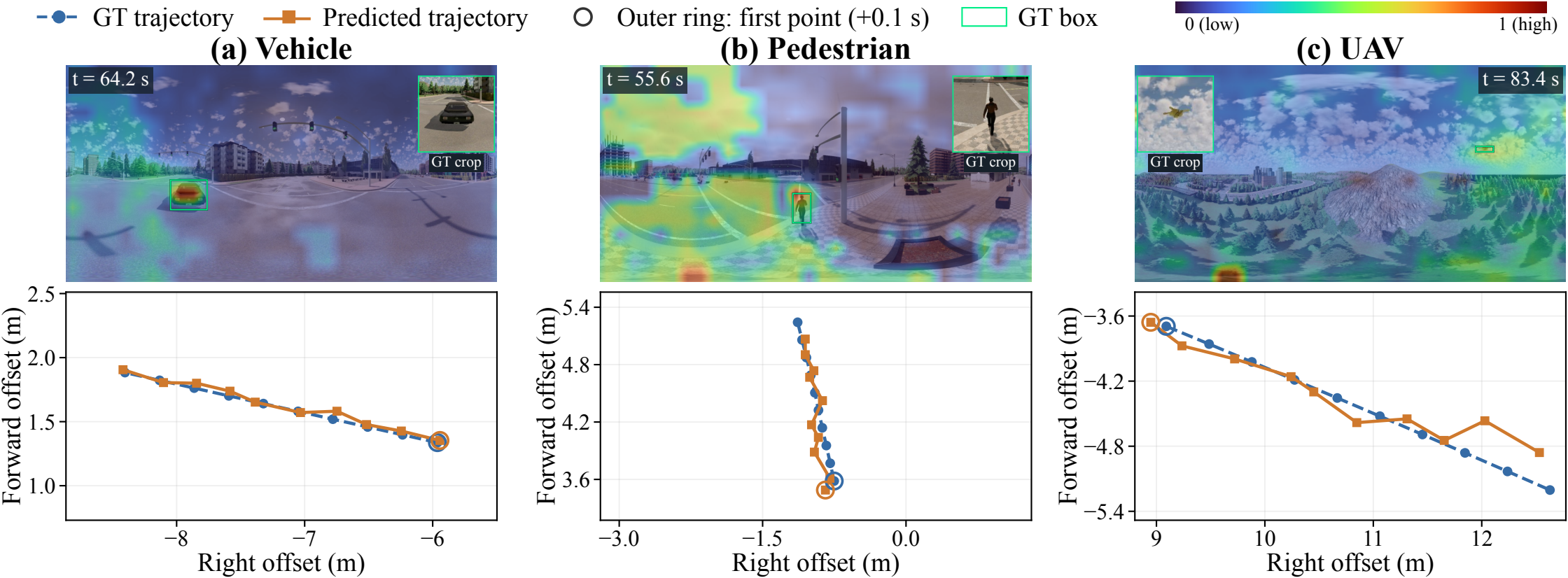

GT trajectory
Predicted trajectory
Outer ring: first point (+0.1 s)
GT box
0 (low)
1 (high)
(a) Vehicle
(b) Pedestrian
(c) UAV
t = 64.2 s
t = 55.6 s
t = 83.4 s
GT crop
GT crop
GT crop
Forward offset (m)
Right offset (m)
2.5
2.0
1.5
1.0
−8
−7
−6
5.4
4.8
4.2
3.6
−3.0
−1.5
0.0
−3.6
−4.2
−4.8
−5.4
9
10
11
12